

MINING
ELECTRICAL
SAFETY 2017
CONFERENCE

Safe Autonomous Production



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M E S A



MINE ELECTRICAL
SAFETY ASSOCIATION INC.

Overview

Why? ... are we even considering this?

What? - Autonomous operation concepts.

Who? - Case Study – Automated Block Cave Copper / Gold Mine.

How? - Safety approach.

But? - Challenges for underground coal and surface mines.

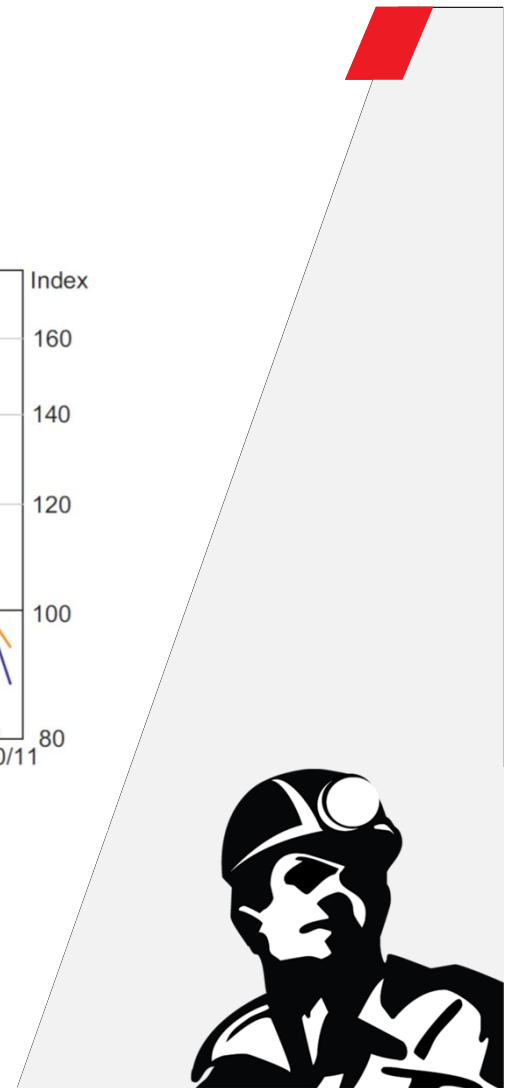
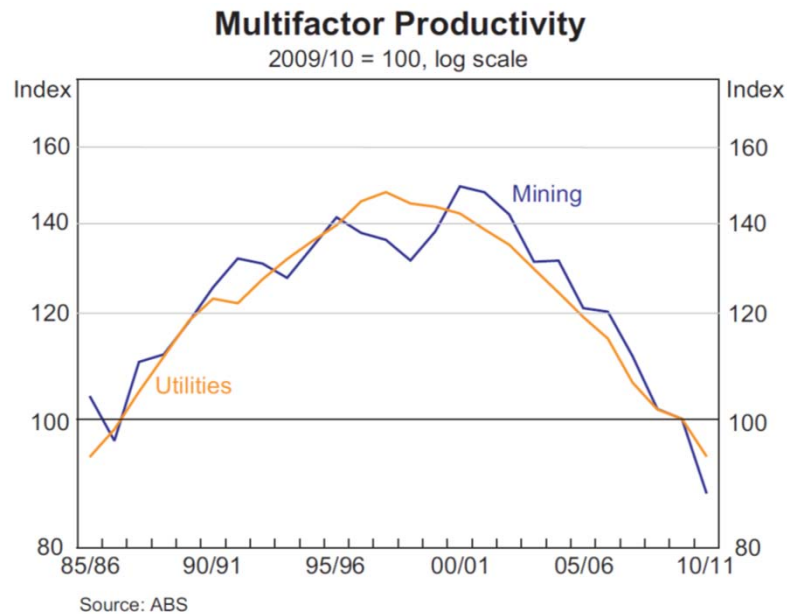
Then? - Lessons learned.



Why? – Mining Industry Productivity

*“...the general slowdown in productivity growth cannot be attributed to weak investment, but is likely to be associated with either **a slowdown in the pace of adoption of productivity-enhancing technological innovations** or less rapid improvement in the efficiency with which capital and labour are employed”.*

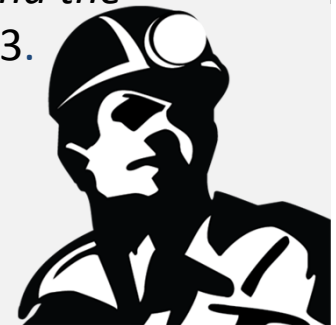
Patrick D’Arcy and Linus Gustafsson, Australia’s Productivity Performance and Real Incomes, Reserve Bank Bulletin, June Quarter 2012.



Why? – 12 Disruptive Technologies (McKinsey)

1. Mobile internet.
2. Automation of knowledge work (non-routine, requiring judgement).
3. The internet of things (web-connected low-cost sensors).
4. Cloud technology.
5. **Advanced robotics.**
6. **Autonomous and near-autonomous vehicles.**
7. Next generation genomics.
8. Energy storage devices.
9. 3D printing.
10. Advanced materials.
11. **Advanced oil / gas exploration & recovery.**
12. **Renewable energy.**

McKinsey & Company - *Disruptive technologies: Advances that will transform life, business, and the global economy*, May 2013.



Why? – Automation ≠ Remote Control

Automation: The use or introduction of automatic equipment in a manufacturing or other process or facility.

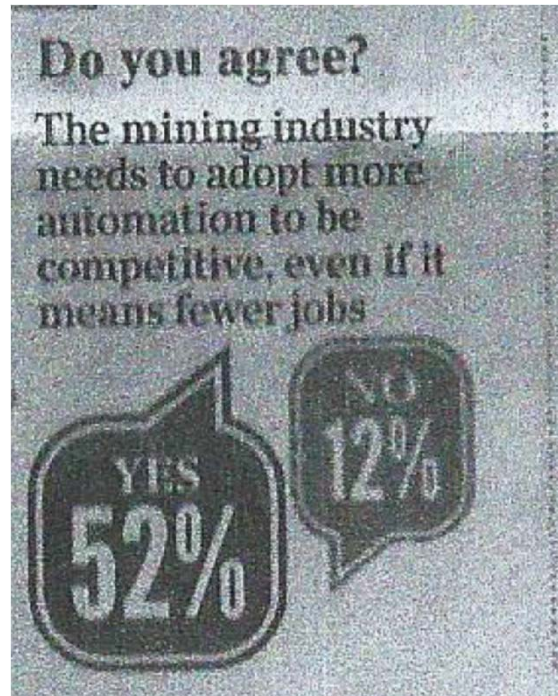
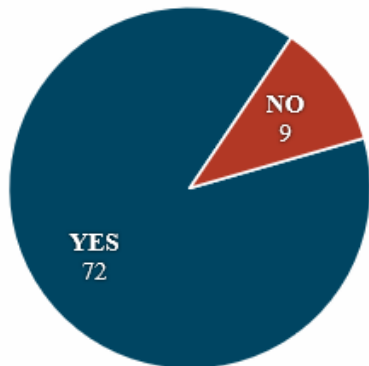
Autonomous: machine that is intended to accomplish its task/s within a set of defined operations without human intervention or direct control.

Semi-autonomous: a machine which requires direct control by a human operator to complete some tasks, while having a portion of its operating cycle not under direct human control.

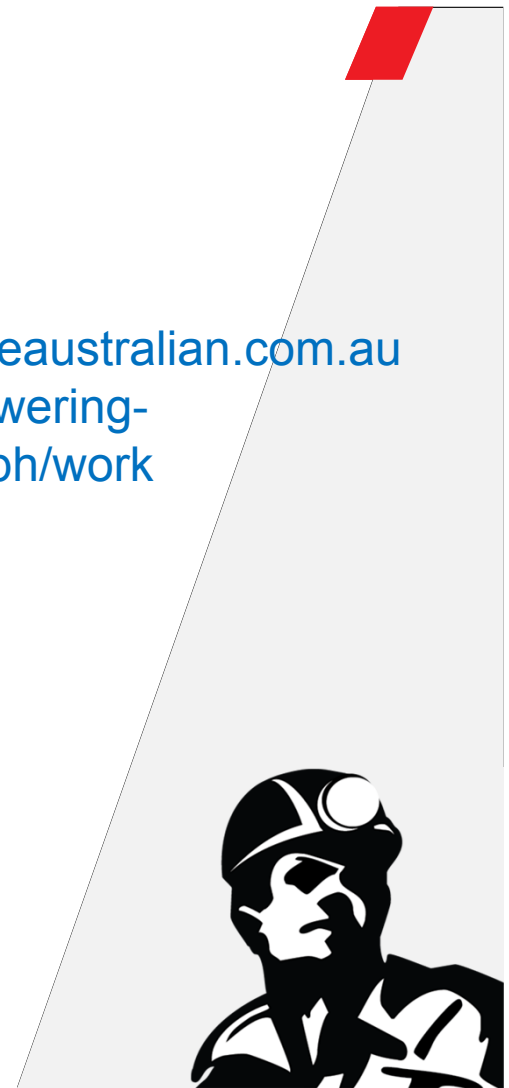


Why? – Automation = Productivity Driver

To be competitive, the Australian industry needs to adopt greater automation, even if it means fewer jobs.



<http://www.theaustralian.com.au/business/powering-australia/graph/work>

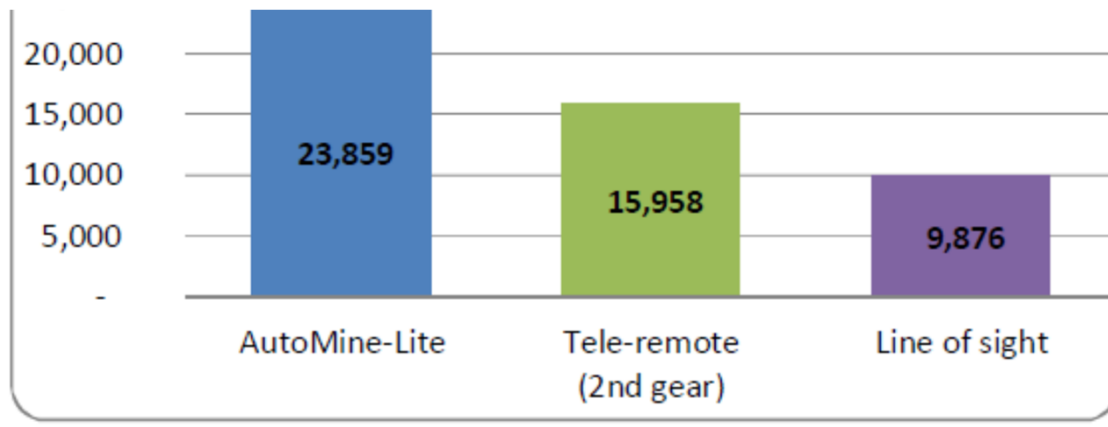


Why? – Automation = Productivity Driver

Autonomous operation is usually initiated as a productivity improvement measure, not usually as a safety improvement measure.

eg. 1.6 times more tonnes / month than tele-remoting.

2.4 times more tonnes / month than LOS remoting.



Source: Sandvik

Improved mine safety is a by-product of automation.



What? – Segregated Autonomous Production

People and autonomous machines are kept separate.

An **Access Control System (ACS)** is placed around the autonomous production zone.



**Access Barrier
(physical and/or electronic)**



What? – Segregated Autonomous Production

ACS keeps machines in and people out.

- Out-of-control machine - automatically de-energised before it exits the autonomous production zone or reaches another machine.
- Person intrudes into an autonomous production zone - machines in that zone are automatically de-energised.

The ACS is controlling the risk.

- Design ACS to a “sufficient” level of reliability for the risk, and independent of the autonomous control system.



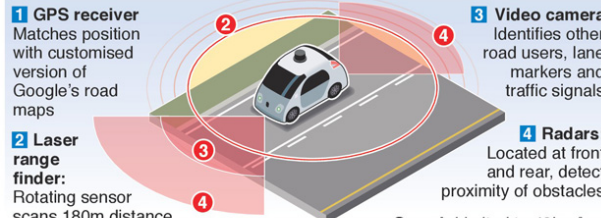
What? – Non-segregated Autonomous Production

People and autonomous machines mingle in the autonomous production zone.

A Proximity Detection / Collision Avoidance System (PD/CAS) protects all entities.

No Access Barrier !

Google unveils self-driving car
Google has begun building a fleet of experimental electric-powered cars that will have a stop-go button but no controls, steering wheel or pedals. Google claims that the two-seater vehicle will revolutionise transport by making roads safer, and decrease congestion and pollution



1 GPS receiver
Matches position with customised version of Google's road maps

2 Laser range finder:
Rotating sensor scans 180m distance through 360° to generate 3D map of surroundings

3 Video camera
Identifies other road users, lane markers and traffic signals

4 Radars:
Located at front and rear, detect proximity of obstacles

Speed: Limited to 40km/h to help ensure safety

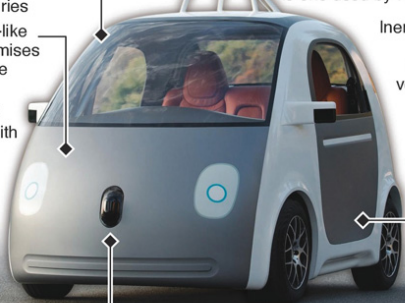
Engine: 160km-range electric motor – equivalent to one used by Fiat's 500e

Windscreen: Flexible plastic designed to reduce injuries

Front: Foam-like material minimises impact in case of crash

Car would be summoned with smartphone application

Inertial motion sensors determine velocity and direction



Source and Picture: Google

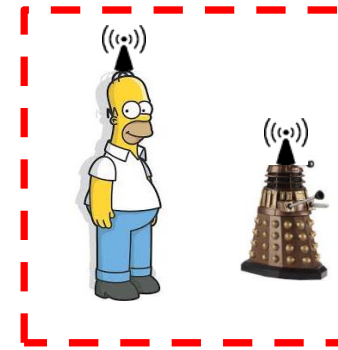
© GRAPHIC NEWS



What? – Non-segregated Autonomous Production

PD/CAS keeps machines and people separated.

- Out-of-control machine - automatically de-energised before it reaches another person or machine.
- Person too close to an autonomous machine - machine automatically de-energised.



The PD/CAS is controlling the risk.

- Design PD/CAS to an “sufficient” level of reliability and independent of the autonomous control system.



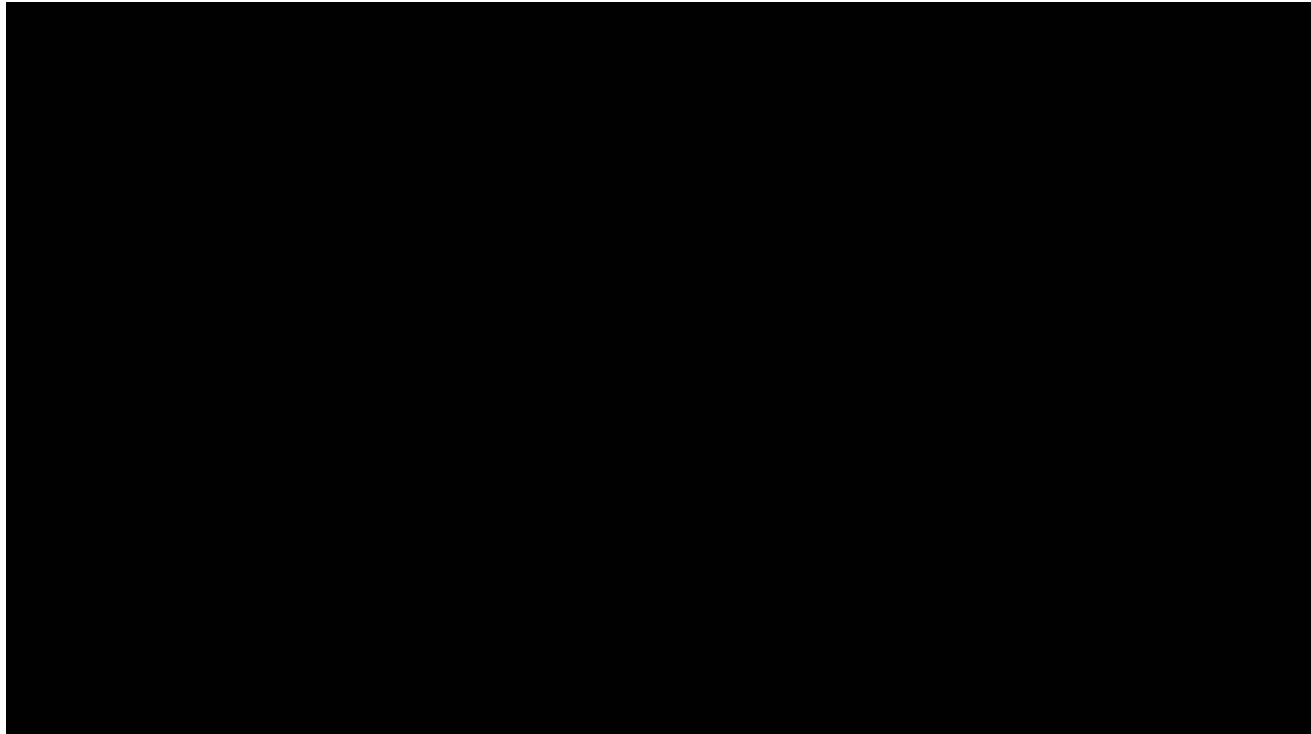
What? – Less Safe Autonomous Production

- Either autonomous control system, PD/CAS or ACS is not designed to a “sufficient” level of reliability – **at least one should be.**
- PD/CAS or ACS not independent of the autonomous control system – **should be.**
eg. same GPS unit used for autonomous guidance and also for PD/CAS.
ie. if GPS provides incorrect or inaccurate positioning, this can affect both the autonomous guidance and the PD/CAS at the same time.
Also: difficult to maintain safety integrity of PD/CAS or ACS due to continual development / optimisation of the automation control system.



Who? – Northparkes Mines

- Segregated (Semi)Autonomous Production.
- SIL2 Access Control System (ACS) – independent of autonomous control.

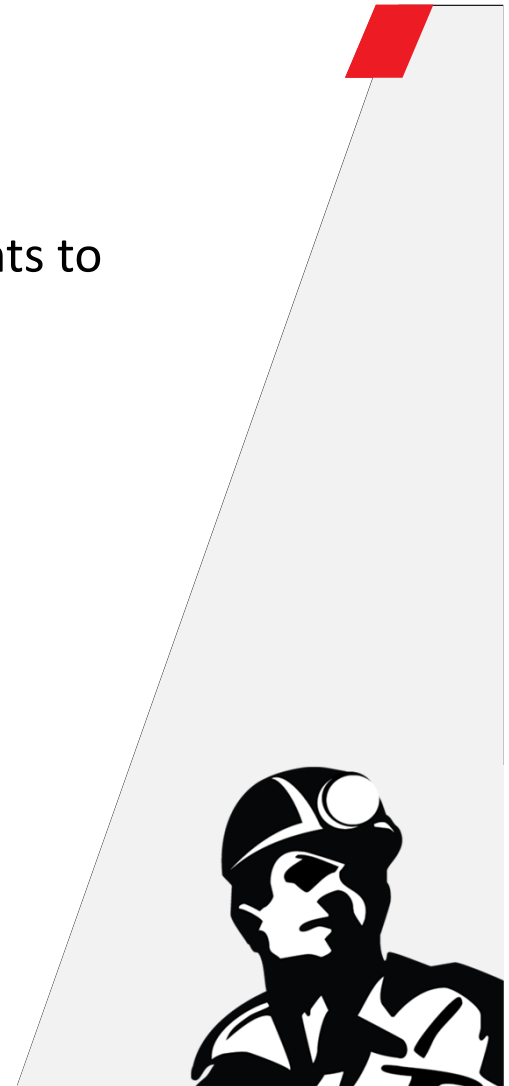
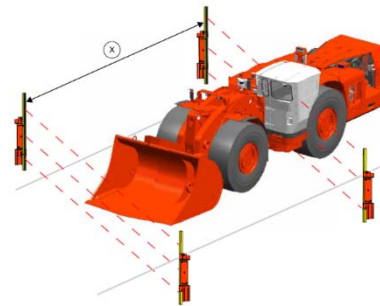
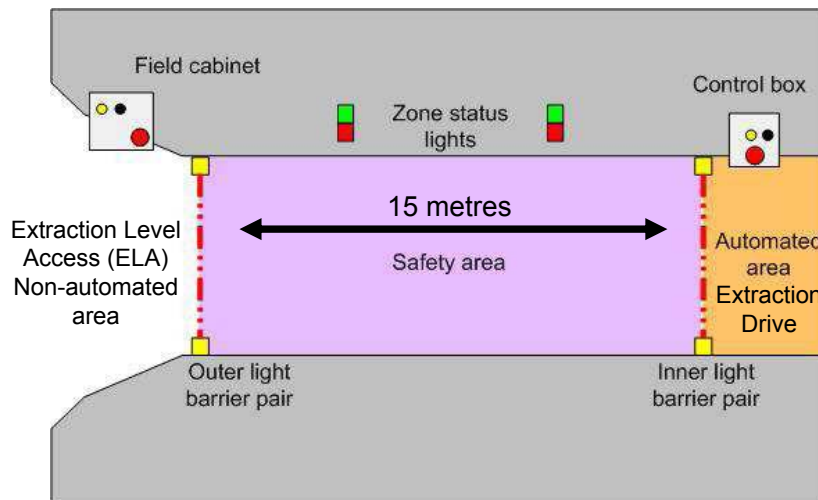


Source: Northparkes
Mines



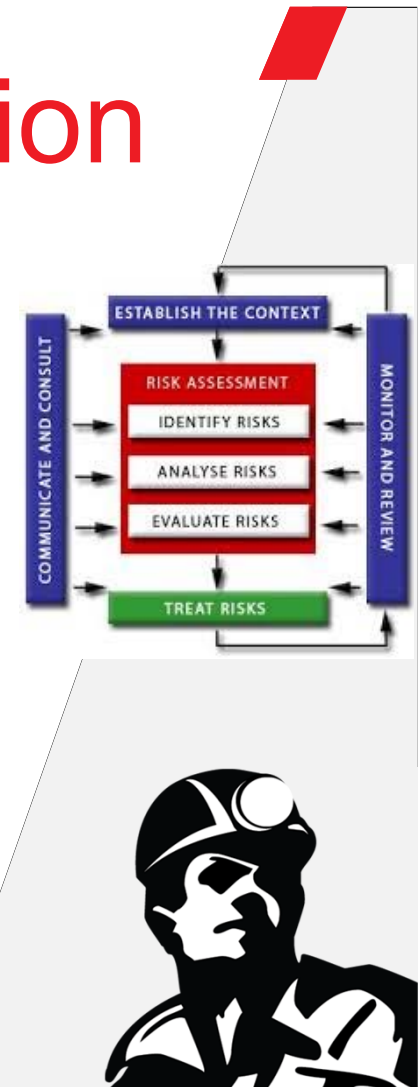
Who? – Sandvik ACS

- Dual light curtains (outer and inner) across entry / exit points to autonomous production zones.
- ACS stop command sent via “wireless” communications.
- SIL2 required. SIL2 capability independently verified.
- Safety area length = comms. delay + braking distance



How? – Control of Automation Risk

- Automation does not eliminate all safety risk.
- It **substitutes** some safety risks. Old risks (of manual operation) are removed. New risks (of autonomous operation) are introduced.
- Care must be taken to control the new risks, so as to ensure a **net safety benefit**.
- New technology → guidelines lag (eg. *ISO/FDIS 17757 (draft) Earth-moving Machinery and Mining— Autonomous and Semi-autonomous Machine System Safety*).
- The solution is to use a risk management approach
 - **identify** “reasonably foreseeable” hazards / risks
 - **analyse** risks (cause, likelihood, degree of harm, available controls)
 - **treat** (control) risks according to the hierarchy of controls (eliminate, substitute...)
 - satisfy the “**reasonably practicable**” test
 - apply “**functional safety approach**” as necessary (ie. for ACS, PD/CAS of “sufficient” reliability for the risk).
 - **communicate & consult** / **monitor & review** .



How? – Automation Risks

A sample of hazards considered in block-cave LHD automation. These could also apply to automation in other types of mines.

- **Person left in autonomous zone** during initialisation.
- **Person enters autonomous zone** (advertantly or inadvertantly).
- **Mine incident** (eg. fire) causing person to attempt escape through autonomous zone.
- **Autonomous machine malfunctions** and tries to leave autonomous zone.
- **Roadway / brakes / tyre condition** - increased braking distances (affects ability to stop machines within autonomous zone).
- **Production control system malfunction** - collisions between autonomous machines.
- **Unplanned movement** during change-over from autonomous mode to manual mode.
- Surface operator - **incapacitation / absence / evacuation**.
- **Human factors** - fatigue / boredom / human error.



But? – Automated Surface Haul Trucks

- Roadways regularly changing → change management.
- Segregated or non-segregated?
- Segregated → How to segregate?
- Non-segregated → accuracy & reliability of PD/CAS?
- High kinetic energies & subject to electronic intervention on brakes

$$E = \frac{1}{2} mv^2$$

720 Tonnes @ 60 km/hr = 100,000,000 Joules

100MJ = 25kg TNT !



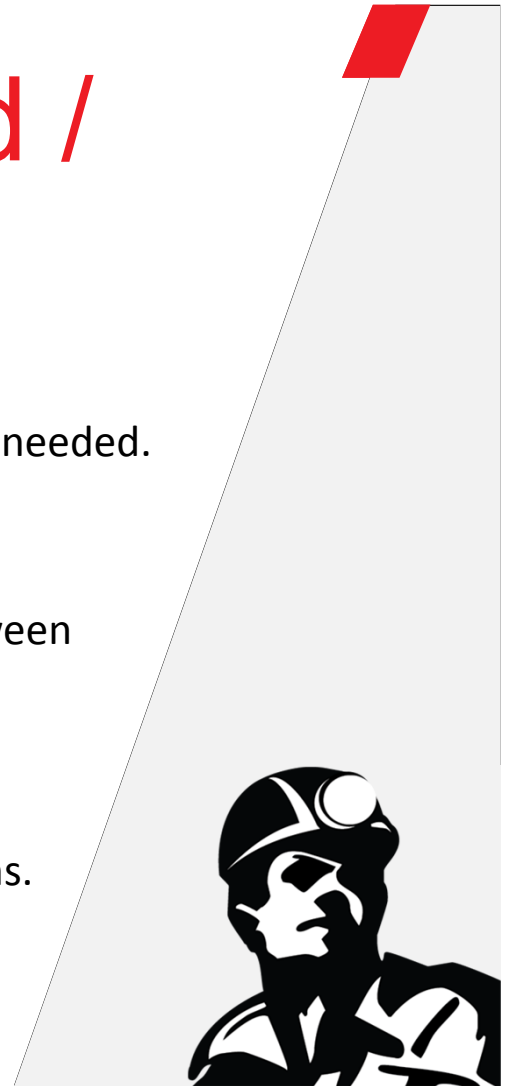
But? – Automated Underground Coal Mines

- Mining areas regularly changing → change management.
- Segregated or non-segregated?
- Segregated → How to segregate?
- Non-segregated → accuracy & reliability of PD/CAS?
- Complex system integration - development and long-wall.
- Ex requirements.



Then? – Lessons Learned / Enablers of Success

- Management and workforce **commitment** is non-negotiable.
- **Innovation** culture / mindset.
- A new **skill-set** (management , engineering / technical, operational) is needed.
- Start the system **safety process early**.
- Evolving software-based technology → **expect bugs**.
- Ensure effective **communication, co-operation and consultation** between project, production and vendor teams.
- **Site-based:**
 - project management.
 - technical experts especially during commissioning / early operations.
 - full-time trainers during introduction.
- Robust **service / maintenance contract**.
- **Question everything!**



Final word....the 10 year space gap...

“The world is moving so fast these days that the man who says it can't be done is generally interrupted by someone doing it”.

- Elbert Green Hubbard



“If we can send a robot into the Solar System to collect rocks relatively unsupervised, surely we can send one into Australia to do it as well.”

- Anon.

